

Math 309 - Worksheet - Linear algebra review

$$A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}, B = \begin{bmatrix} i & 1 \\ 1 & -i \end{bmatrix}, C = \begin{bmatrix} 3 & i \\ -i & 1 \end{bmatrix}, F = \begin{bmatrix} 1 & -2 & 3 \\ -1 & 1 & -2 \\ 2 & -1 & 3 \end{bmatrix}, v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

1. **Determinant:** Compute $\det B$, $\det C$, $\det F$.

Formulas : $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$

$$\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & l \end{pmatrix} = a \det \begin{pmatrix} e & f \\ h & l \end{pmatrix} - b \det \begin{pmatrix} d & f \\ g & l \end{pmatrix} + c \det \begin{pmatrix} d & e \\ g & h \end{pmatrix}$$

$$\det B = i(-i) - 1 = 0$$

$$\det C = 3 - (-i)i = 2$$

$$\det F = 1(3-2) + 2(-3+4) + 3(1-2) = 1 + 2 - 3 = 0$$

Fact :

$\det M = 0 \Leftrightarrow$ rows are linearly dependent

\Leftrightarrow columns are linearly dependent

$\Leftrightarrow M$ not invertible

For 2×2 matrices

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0 \Leftrightarrow [a \ b] = r[c \ d] = [rc \ rd] \\ \text{for some } r \in \mathbb{C}$$

2. Linear systems with invertible matrix:

Consider the equation $Cx = v$ where $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$.

$$\begin{bmatrix} 3 & i \\ -i & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \iff \begin{cases} 3x_1 + ix_2 = 1 & \textcircled{1} \\ -ix_1 + x_2 = 2 & \textcircled{2} \end{cases}$$

Find the solution to $Cx = v$.

$$\textcircled{2} \Rightarrow x_2 = 2 + ix_1$$

$$\textcircled{1} \Rightarrow 3x_1 + i(2 + ix_1) = 1$$

$$2x_1 = 1 - 2i$$

$$\begin{cases} x_1 = \frac{1}{2} - i \end{cases}$$

$$\begin{cases} x_2 = 2 + ix_1 = 2 + i(\frac{1}{2} - i) = 3 + \frac{i}{2} \end{cases}$$

Method 2: $Cx = v$

Formula:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$\det C \neq 0$
so C^{-1} exists

$$\Rightarrow \underbrace{C^{-1}C}_I x = C^{-1}v$$

$$\Rightarrow x = C^{-1}v = \frac{1}{2} \begin{bmatrix} 1 & -i \\ i & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} - i \\ \frac{i}{2} + 3 \end{bmatrix}$$

Find the solution to $Cx = 0$ (homogeneous equation).

$$\Rightarrow x = C^{-1}0 = 0, \text{ i.e. } \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ trivial solution}$$

Fact: $\det C \neq 0$

$\Rightarrow Cx = v$ has a unique solution $x = C^{-1}v$.

$\Rightarrow Cx = 0$ " " " " $x = 0$.

3. Linear systems with noninvertible matrix:

Find the set of solutions to $Bx = 0$.

$$\begin{bmatrix} i & 1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \iff \begin{cases} ix_1 + x_2 = 0 & \textcircled{1} \\ x_1 - ix_2 = 0 & \textcircled{2} \end{cases}$$

$$\iff \begin{cases} ix_1 + x_2 = 0 \\ i\textcircled{2} - \textcircled{1}: 0 + 0 = 0 \end{cases} \quad \begin{array}{l} \text{Redundant equations} \\ \text{due to } \det B = 0 \end{array}$$

$$\iff ix_1 + x_2 = 0, \text{ i.e. } x_2 = -ix_1$$

$$\text{Set of soln: } \left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ -ix_1 \end{bmatrix} = \begin{bmatrix} 1 \\ -i \end{bmatrix} x_1, x_1 \in \mathbb{R} \right\} \quad \text{has dim} = 1$$

Find the set of solutions to $Bx = v$.

$$\begin{bmatrix} i & 1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \iff \begin{cases} ix_1 + x_2 = 1 & \textcircled{1} \\ x_1 - ix_2 = 2 & \textcircled{2} \end{cases}$$

$$\iff \begin{cases} ix_1 + x_2 = 1 \\ i\textcircled{2} - \textcircled{1}: 0 = 2i - 1 \end{cases}$$

⚡ contradiction

no solution

Find the set of solutions to $Bx = \begin{bmatrix} 1 \\ -i \end{bmatrix}$.

$$\begin{bmatrix} i & 1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ -i \end{bmatrix} \iff \begin{cases} ix_1 + x_2 = 1 & \textcircled{1} \\ x_1 - ix_2 = -i & \textcircled{2} \end{cases}$$

$$\iff \begin{cases} ix_1 + x_2 = 1 \\ i\textcircled{2} - \textcircled{1}: 0 = 0 \end{cases}$$

$$\iff ix_1 + x_2 = 1, \text{ i.e. } x_2 = 1 - ix_1$$

Set of soln:

$$\left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ 1-ix_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \underbrace{\begin{bmatrix} 1 \\ -i \end{bmatrix}}_{\text{soln to } Bx=0} x_1, x_1 \in \mathbb{R} \right\} \text{ has } \dim=1$$

Fact: $\det B = 0$

$\Rightarrow Bx=0$ has infinitely many solutions

$\Rightarrow Bx=v$ either has no solution or
has infinitely many solutions

4. Linear systems with noninvertible matrix cont'd:

Find the set of solutions to $Fx = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

$$\begin{bmatrix} 1 & -2 & 3 \\ -2 & 1 & -2 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \iff \begin{cases} x_1 - 2x_2 + 3x_3 = 0 & \textcircled{1} \\ -x_1 + x_2 - 2x_3 = 0 & \textcircled{2} \\ 2x_1 - x_2 + 3x_3 = 0 & \textcircled{3} \end{cases}$$

$$\textcircled{1} + \textcircled{2} \Rightarrow \begin{aligned} -x_2 + x_3 &= 0 \\ x_2 &= x_3 \end{aligned}$$

$$\textcircled{2} \Rightarrow \begin{aligned} -x_1 + x_3 - 2x_3 &= 0 \\ x_1 &= -x_3 \end{aligned}$$

$$\textcircled{3} \Rightarrow \begin{aligned} -2x_3 - x_3 + 3x_3 &= 0 \\ 0 &= 0, \quad x_3 \text{ arbitrary} \end{aligned}$$

Solution set

$$\left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} x_3, \quad x_3 \in \mathbb{R} \right\}$$

Alternatively, more systematically, can do

$$\textcircled{1} \Rightarrow x_1 = 2x_2 - 3x_3$$

$$\textcircled{2} \Rightarrow -(2x_2 - 3x_3) + x_2 - 2x_3 = 0$$

$$\Rightarrow x_2 = x_3, \quad \text{so } x_1 = 2x_2 - 3x_3 = -x_3$$

$$\textcircled{3} \Rightarrow -2x_3 - x_3 + 3x_3 = 0, \quad x_3 \text{ arbitrary}$$

5. **Linear (in)dependence:**

Are the three column vectors of F linearly independent? If they are linearly dependent, find a linear relation among them.

Column vectors are dependent since $\det F = 0$.

So want to find c_1, c_2, c_3 , not all 0, s.t.

$$c_1 \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix} + c_3 \begin{bmatrix} 3 \\ -2 \\ 3 \end{bmatrix} = 0$$

i.e.

$$\begin{bmatrix} 1 & -2 & 3 \\ -1 & 1 & -2 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We already found answers to this in Problem 4 that

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} c_3, \text{ where any } c_3 \in \mathbb{R} \text{ will do.}$$

Pick $c_3 = 1$

$$- \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 3 \\ -2 \\ 3 \end{bmatrix} = 0$$

Note about linear independence.

Vectors $\vec{v}_1, \dots, \vec{v}_n$ are linearly independent if

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

$$\Rightarrow c_1 = c_2 = \dots = c_n = 0$$

Note: If $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$ but at least one of the c 's is not zero, say $c_2 \neq 0$. Then

$$c_2 \vec{v}_2 = -c_1 \vec{v}_1 - c_3 \vec{v}_3$$

$$\vec{v}_2 = -\frac{c_1}{c_2} \vec{v}_1 - \frac{c_3}{c_2} \vec{v}_3 \quad (\text{can divide by } c_2 \text{ because } c_2 \neq 0)$$

i.e. \vec{v}_2 is a linear combination of \vec{v}_1 and \vec{v}_3 .

So, $\vec{v}_1, \vec{v}_2, \vec{v}_3$ dependent

Example: suppose $\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4$ are linearly independent

and $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 + c_4 \vec{v}_4 = 7 \vec{v}_2$

What are c_1, c_2, c_3, c_4 ?

Answer: $c_1 = c_3 = c_4 = 0, c_2 = 7$ (just match the coefficients)

This is because

$$c_1 \vec{v}_1 + (c_2 - 7) \vec{v}_2 + c_3 \vec{v}_3 + c_4 \vec{v}_4 = \vec{0}$$

linear independence $\Rightarrow c_1 = c_2 - 7 = c_3 = c_4 = 0$

6. Eigenvalues and eigenvectors:

Given a matrix M , if $Mx = \lambda x$, equivalently $(M - \lambda I)x = 0$, for some $x \neq 0$, then λ is an **eigenvalue** of M and x is an **eigenvector** of M corresponding to λ .

Note that there exists $x \neq 0$ such that $(M - \lambda I)x = 0$ if and only if $\det(M - \lambda I) = 0$.

(a) Find all the eigenvalues of the matrix A and the set of eigenvectors corresponding to each eigenvalue.

$$A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

(b) Write $A = PDP^{-1}$ where D is a diagonal matrix with the diagonal entries being the eigenvalues.

Find eigenvalue:

$$0 = \det(A - \lambda I) = \det \begin{pmatrix} 2-\lambda & -1 \\ -1 & 2-\lambda \end{pmatrix} = (2-\lambda)^2 - 1 = \lambda^2 - 4\lambda + 3 = (\lambda-1)(\lambda-3)$$

$$\boxed{\lambda_1 = 1}, \quad \boxed{\lambda_2 = 3}$$

Eigenvector corresp. to $\lambda_1 = 1$

$$\text{Solve } (A - \lambda_1 I)v = 0$$

$$\begin{bmatrix} 2-1 & -1 \\ -1 & 2-1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \iff v_1 - v_2 = 0, \text{ i.e. } v_1 = v_2$$

set of eigenvectors corresponding to $\lambda_1 = 1$:

$$\left\{ \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} v_1, \quad v_1 \neq 0 \right\}$$

Eigenvector corresp. to $\lambda_2 = 3$

$$\text{Solve } (A - \lambda_2 I)w = 0$$

$$\begin{bmatrix} 2-3 & -1 \\ -1 & 2-3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \iff -w_1 - w_2 = 0, \text{ i.e. } w_1 = -w_2$$

set of eigenvectors corresponding to $\lambda_2 = 3$:

$$\left\{ \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} w_2, \quad w_2 \neq 0 \right\}$$

$$(b) \quad P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}, \quad A = P \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}}_D P^{-1}$$

\uparrow \uparrow \uparrow
 eigenvec eigenvec
 for λ_1 for λ_2

A note about complex numbers :

* $i^2 = -1$

$$* \frac{1}{3+4i} = \frac{3-4i}{(3+4i)(3-4i)} = \frac{3-4i}{3^2+4^2} = \frac{1}{25} (3-4i)$$

* $\lambda = a+bi, \bar{\lambda} = a-bi$

if M is real,

then { if v is an eigenvector with eigenvalue λ , i.e. $Mv = \lambda v$

then $\boxed{M\bar{v}} = \overline{Mv} = \overline{\lambda v} = \overline{\lambda} \bar{v} = \boxed{\bar{\lambda} \bar{v}}$

i.e. \bar{v} is an eigenvector with eigenvalue $\bar{\lambda}$