

$x' = Ax$  ,  $A$   $2 \times 2$  complex eigenvalues

Ex1  $x' = \underbrace{\begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix}}_A x$

Eigenval:  $0 = \det \begin{bmatrix} -1-\lambda & -2 \\ 8 & -1-\lambda \end{bmatrix} = (-1-\lambda)^2 + 16 = \lambda^2 + 2\lambda + 17$

$$\lambda = \frac{-2 \pm \sqrt{4 - 68}}{2} = -1 \pm 4i$$

Fact: If  $A$  is real,  $v$  an eigenvector w/ eigenvalue  $\lambda$

$\Leftrightarrow \bar{v}$  is an eigenvector w/ eigenvalue  $\bar{\lambda}$ .

reason:  $Av = \lambda v$

$$\Leftrightarrow A\bar{v} = \overline{Av} = \overline{\lambda v} = \bar{\lambda} \bar{v}$$

Eigenvector for  $\boxed{\lambda = -1 + 4i}$  (pick one)

solve  $(A - \lambda I)v = 0$

$$\begin{bmatrix} -4i & -2 \\ 8 & -4i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \rightsquigarrow \begin{aligned} -4iv_1 - 2v_2 &= 0 \\ \Rightarrow v_2 &= -2iv_1 \end{aligned}$$

$$v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ -2iv_1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2i \end{bmatrix} v_1, \quad v_1 \neq 0$$

Pick one:  $\boxed{v = \begin{bmatrix} 1 \\ -2i \end{bmatrix}}$



Reason 1:  $y = u + iv$ ,  $y' = Ay$

$$(u + iv)' = A(u + iv)$$

$$u' + iv' = Au + iAv$$

$$\Rightarrow \begin{cases} u' = Au \\ v' = Av \end{cases}$$

Reason 2

$$\left. \begin{array}{l} y = u + iv \\ \bar{y} = u - iv \end{array} \right\} \begin{array}{l} \text{Change of} \\ \text{basis} \end{array} \rightarrow \begin{cases} u = \frac{y + \bar{y}}{2} = \operatorname{Re} y \\ v = \frac{y - \bar{y}}{2i} = \operatorname{Im} y \end{cases}$$

Gen soln to  $x' = Ax$  in terms of real basis is

$$\boxed{x = C_1 \operatorname{Re} y + C_2 \operatorname{Im} y}$$

$$X = C_1 \left( e^{-t} \cos 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} - e^{-t} \sin 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right) + C_2 \left( e^{-t} \sin 4t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{-t} \cos 4t \begin{bmatrix} 0 \\ -2 \end{bmatrix} \right)$$

$$= C_1 \begin{bmatrix} e^{-t} \cos 4t \\ 2e^{-t} \sin 4t \end{bmatrix} + C_2 \begin{bmatrix} e^{-t} \sin 4t \\ -2e^{-t} \cos 4t \end{bmatrix} \quad \text{As } t \rightarrow \infty, \\ x(t) \rightarrow 0$$

$$x(t) = e^{-t} \begin{bmatrix} \cos 4t & \sin 4t \\ 2 \sin 4t & -2 \cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$$

$$= e^{-t} \begin{bmatrix} \cos 4t & -\frac{\sin 4t}{2} \\ 2\sin 4t & \cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ -2C_2 \end{bmatrix}$$

$$x(0) = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} C_1 \\ -2C_2 \end{bmatrix}$$

$$= e^{At} x(0)$$

Ex2 :  $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$  ,  $x' = Ax$

Eigenval :  $\pm i$  , pick  $\lambda = i$

Corresp. Eigenvec :  $V = \begin{bmatrix} 1 \\ i \end{bmatrix}$

$$y = e^{it} \begin{bmatrix} 1 \\ i \end{bmatrix} = (\cos t + i \sin t) \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

$$x(t) = C_1 \operatorname{Re}(y) + C_2 \operatorname{Im}(y)$$

$$= C_1 \left( \cos t \begin{bmatrix} 1 \\ 0 \end{bmatrix} - \sin t \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) + C_2 \left( \sin t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \cos t \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

$$= C_1 \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + C_2 \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

$$X(t) = e^{At} \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$$

$= e^{At} X(0)$

$$X(0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$$

RMk:  $e^{At} = P e^{Dt} P^{-1} = P \begin{bmatrix} e^{it} & 0 \\ 0 & e^{-it} \end{bmatrix} P^{-1} = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix}$

$A = P D P^{-1}$

$P = \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix}, D = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$

HW4  
#2

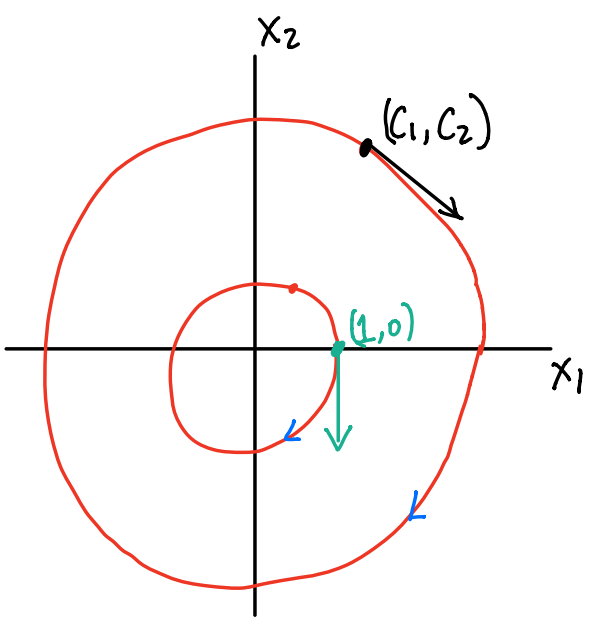
Ex 2 cont'd

$x_1 = C_1 \cos t + C_2 \sin t$

$x_2 = -C_1 \sin t + C_2 \cos t$

can verify :  $x_1^2 + x_2^2 = C_1^2 + C_2^2$

circle centered at the origin of radius  $\sqrt{C_1^2 + C_2^2}$



$X(0) = \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$

$X'(0) = A X(0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} C_2 \\ -C_1 \end{bmatrix}$

\* all circles go in the same direction, so can use any "easy" initial condition to check the direction

Easy test case: when  $x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$x'(0) = Ax(0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Ex 3 sketch  $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \cos 4t & \sin 4t \\ 2\sin 4t & -2\cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$

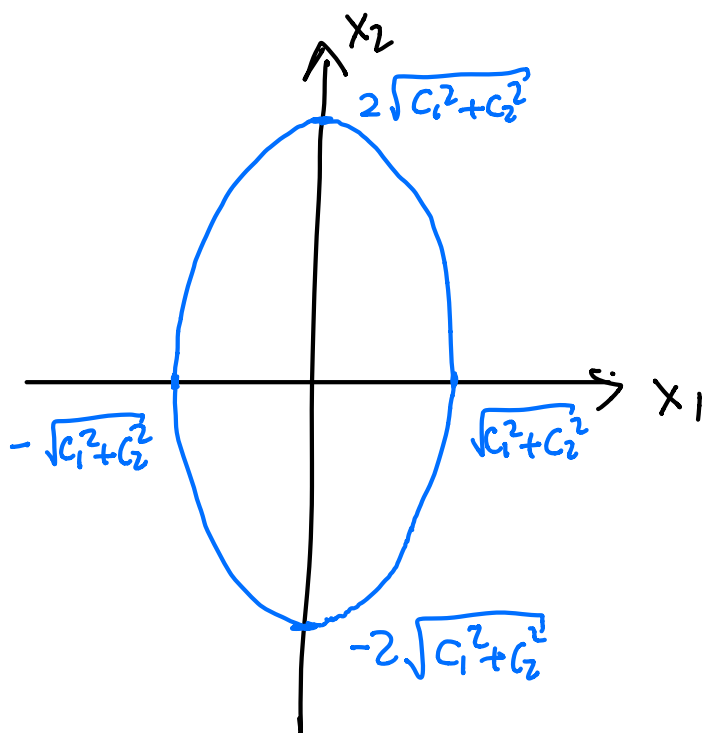
$$x_1 = C_1 \cos 4t + C_2 \sin 4t$$

$$x_2 = 2(C_1 \sin 4t - C_2 \cos 4t)$$

Can verify  $x_1^2 + \left(\frac{x_2}{2}\right)^2 = C_1^2 + C_2^2$

$\Rightarrow$  ellipse centered at the origin

$\Rightarrow$  axis of the ellipse =  $x_1, x_2$  axes



$$\left(\frac{x_1}{a}\right)^2 + \left(\frac{x_2}{b}\right)^2 = C \quad \text{has "straight" axis}$$

RMK: HW 5 # 1 find axes for ellipse with tilted axis.

In general:

If  $\lambda = ib$  (purely imaginary)

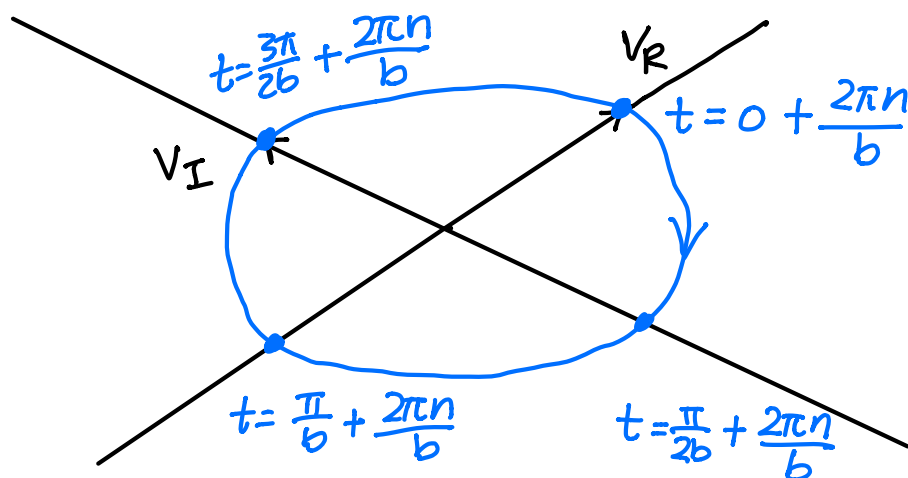
$$V = V_R + iV_I$$

One real soln is

$$\text{Re}(e^{ibt} v)$$

$$= \text{Re}\left((\cos bt + i \sin bt)(V_R + iV_I)\right)$$

$$= \cos(bt) V_R - (\sin bt) V_I$$



,  $n \in \mathbb{Z}$

\* But  $V_I$  and  $V_R$  may not be axes of the ellipse, not when  $V_I$  and  $V_R$  are not  $\perp$ .

\* other trajectories are concentric ellipses

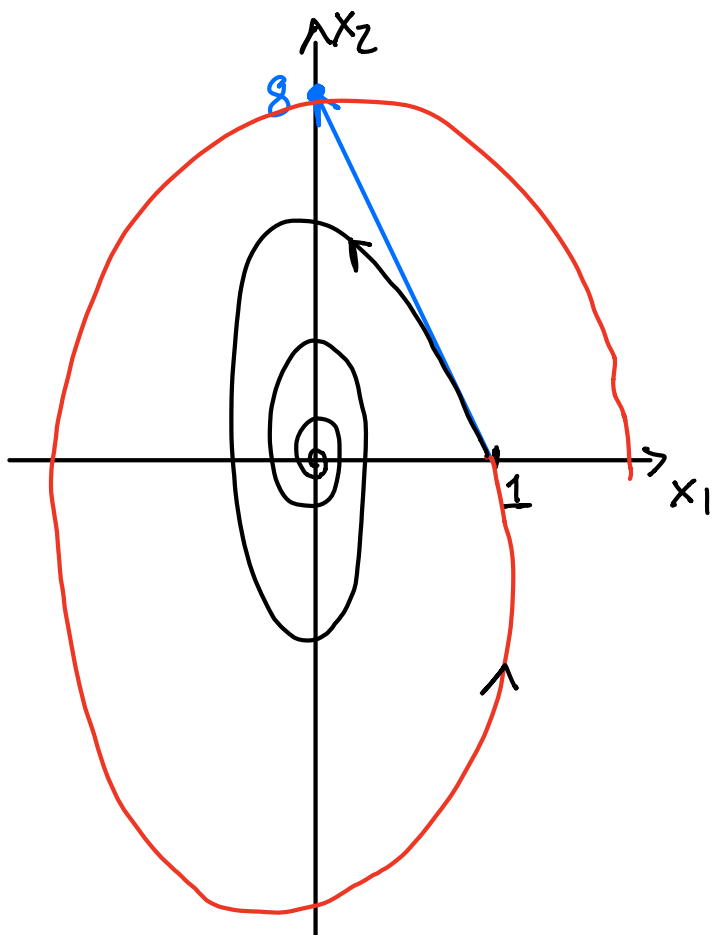
Ex 1 (cont'd) eigenvalue  $\lambda = a \pm bi$ ,  $a \neq 0$

$$x(t) = e^{-t} \begin{bmatrix} \cos 4t & \sin 4t \\ 2 \sin 4t & -2 \cos 4t \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} \quad \text{elliptical spiral}$$

$$x' = Ax, \quad A = \begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix}, \quad x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$x'(0) = Ax(0)$$

$$= \begin{bmatrix} -1 & -2 \\ 8 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 8 \end{bmatrix}$$



$$\text{⌚} \quad t \in [0, \infty)$$

$$\text{⌚} \quad t \leq 0$$

Stable spiral

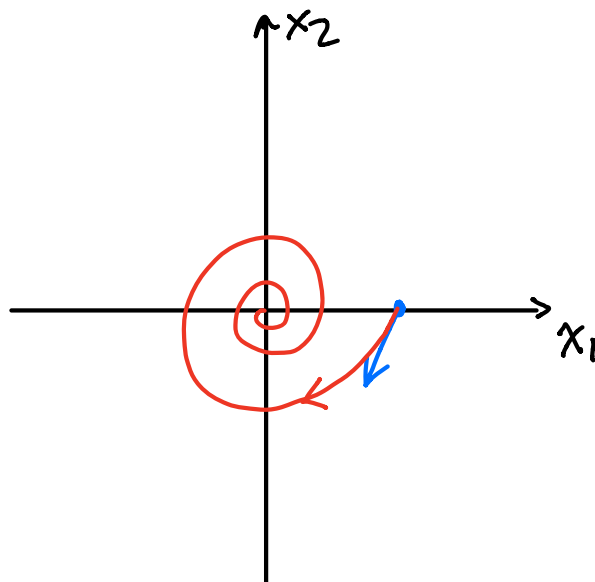
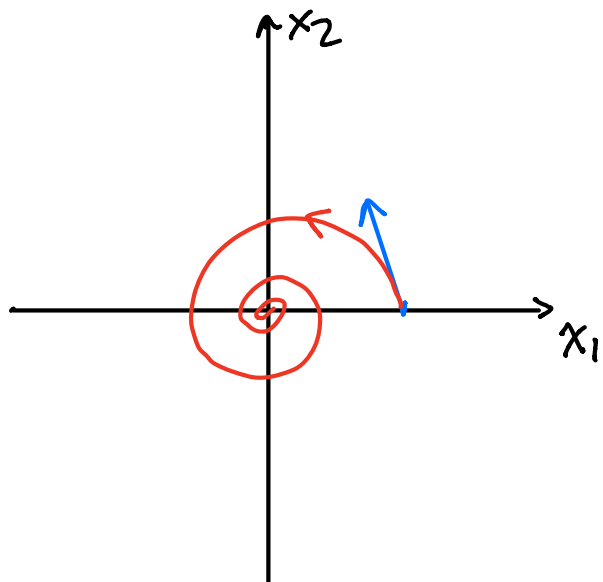
counterclockwise



# Different spiral

Stable  
Spiral

trajectory for  $t \geq 0$



Unstable  
Spiral

