

Homogeneous Linear 2nd Order diff eqn's w/

Constant coefficients §3.1-3.4

Ex: $m \frac{dv}{dt} = -mg - \gamma v$ (1st order linear eqn)

$$m \frac{d^2y}{dt^2} = -mg - \gamma \frac{dy}{dt}$$

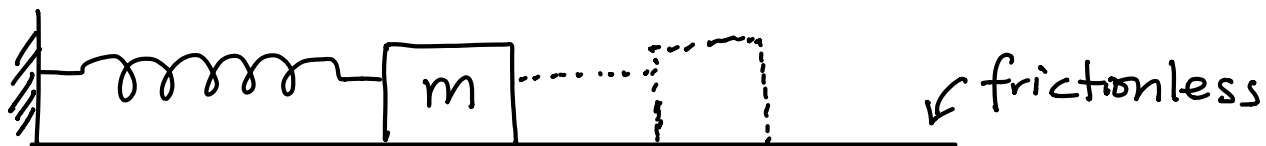
(y = position)

$$\textcircled{m} y'' + \textcircled{\gamma} y' = \textcircled{-mg} \quad \text{(2nd order linear eqn)}$$

$\neq 0$, so not homog.
 $y(t) = 0$ not a soln.

const. coeff.

Ex (spring-mass system)



$u=0$
equilibrium
position

u = displacement from
equilibrium
(positive when stretched)

$$m \frac{d^2u}{dt^2} = F_{\text{spring}} = -ku \quad \text{(Hooke's law)}$$

important comment said verbally in lecture but didn't write down:
force due to spring always opposes displacement, so there's
always an "-" sign regardless of our choice of coordinates

$k = \text{spring constant}$, $[k] = \text{kg/s}^2$

$$\boxed{m u'' + k u = 0} \quad (\text{2nd order linear eqn})$$

\swarrow const. coeff. \swarrow homog.

Indeed, $u(t) = 0$ is a soln.

Harmonic oscillator

Initial condition : $u(0)$ and $u'(0)$

Ex 0 : $y' = 3y$, $y' - 3y = 0$

$$y = A e^{3t}$$

Ex 1 : $\boxed{y'' - 8y' + 15y = 0}$

Try to see if there are soln's of the form $y = e^{rt}$.

$$0 = r^2 e^{rt} - 8r e^{rt} + 15 e^{rt}$$

$$0 = e^{rt} (r^2 - 8r + 15)$$

characteristic eqn: $\boxed{r^2 - 8r + 15 = 0}$

$$(r-3)(r-5) = 0$$

Two distinct real roots: $r=3, 5$

$$y_1 = e^{3t}, \quad y_2 = e^{5t} \quad \text{are soln's.}$$

$$(Ay_1 + By_2)'' - 8(Ay_1 + By_2)' + 15(Ay_1 + By_2)$$

linear \nearrow

$$= A(\underbrace{y_1'' - 8y_1' + 15y_1}_{=0}) + B(\underbrace{y_2'' - 8y_2' + 15y_2}_{=0})$$

homog. \nearrow $= 0$

$\Rightarrow Ay_1 + By_2$ are all solutions

(in fact, these are all the solutions)

$$L[y] = y'' - 8y' + 15y \quad \text{linear operator}$$

$$L[Ay_1 + By_2] = AL[y_1] + BL[y_2]$$

$$\boxed{y = Ae^{3t} + Be^{5t}}$$

Arbitrary constants are determined by initial

conditions $\boxed{y(0) = 1, \quad y'(0) = 2}$

$$y'(t) = 3Ae^{3t} + 5Be^{5t}$$

$$\left. \begin{aligned} 1 = y(0) &= A + B \\ 2 = y'(0) &= 3A + 5B \end{aligned} \right\} \begin{aligned} B &= 1 - A \\ 2 &= 3A + 5(1 - A) \\ 2A &= 3 \\ A &= \frac{3}{2}, \quad B = -\frac{1}{2} \end{aligned}$$

$$\boxed{y(t) = \frac{3}{2}e^{3t} - \frac{1}{2}e^{5t}}$$

End of lecture 1

Ex2 $y'' + 4y' + 13y = 0$

char eqn: $r^2 + 4r + 13 = 0$

$$r = \frac{-4 \pm \sqrt{16 - 52}}{2} = \frac{-4 \pm \sqrt{-36}}{2}$$

$$r = -2 \pm 3i \quad (\text{complex roots})$$

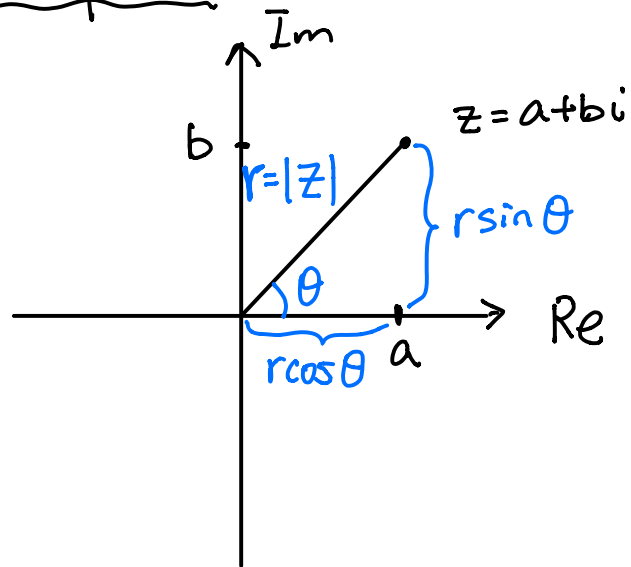
$$\boxed{y(t) = C_1 e^{(-2+3i)t} + C_2 e^{(-2-3i)t}}$$

Complex numbers and functions

$$z = a + ib$$

$$i^2 = -1$$

Complex plane



$$|z|^2 = |a+ib|^2 = a^2 + b^2$$

$$\begin{aligned} |a+ib|^2 &= (a+ib)(a-ib) \\ &= a^2 + iba - iab + b^2 = a^2 + b^2 \end{aligned}$$

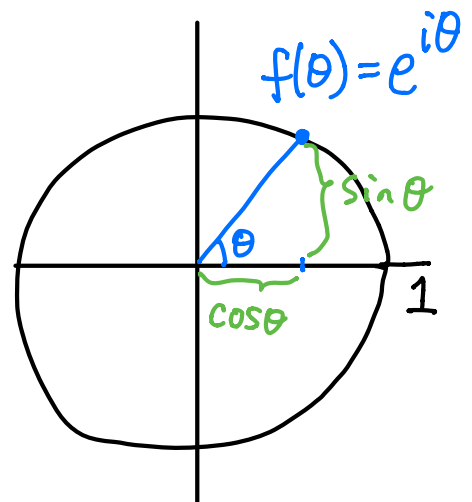
$$\begin{aligned} \frac{1}{a+ib} &= \frac{a-ib}{(a+ib)(a-ib)} = \frac{a-ib}{a^2+b^2} \\ &= \frac{a}{a^2+b^2} - i \frac{b}{a^2+b^2} \end{aligned}$$

Polar coordinates

$$\begin{aligned} z &= a + ib \\ &= r \cos \theta + i r \sin \theta \end{aligned}$$

$$f(\theta) = \cos \theta + i \sin \theta$$

$$f'(\theta) = -\sin \theta + i \cos \theta$$



$$= i \underbrace{(\cos \theta + i \sin \theta)}_{f(\theta)}$$

$$f(\theta) \text{ satisfies } \left. \begin{array}{l} f' = if \\ f(0) = 1 \end{array} \right\} \Rightarrow f(\theta) = e^{i\theta}$$

Euler's formula

$$\left[\begin{array}{l} e^{i\theta} = \cos \theta + i \sin \theta \\ e^{\alpha + i\beta} = e^{\alpha} e^{i\beta} = e^{\alpha} (\cos \beta + i \sin \beta) \end{array} \right.$$

Another explanation for Euler's formula (optional)

$f(z) = e^z$ is defined by $\left\{ \begin{array}{l} f' = f \\ f(0) = 1 \end{array} \right\} \Rightarrow$ Taylor expansion of f at 0.

$$f(z) = e^z = 1 + z + \frac{z^2}{2!} + \frac{z^3}{3!} + \frac{z^4}{4!} + \dots$$

$$f(i\theta) = e^{i\theta} = 1 + i\theta + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \frac{(i\theta)^4}{4!} + \dots$$

$$= 1 + i\theta - \frac{\theta^2}{2!} - i\frac{\theta^3}{3!} + \frac{\theta^4}{4!} + \dots$$

$$= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} + \dots \right) + i \left(\theta - \frac{\theta^3}{3!} + \dots \right)$$

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$e^{-i\theta} = \cos \theta - i \sin \theta$$

$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

Ex2 cont'd

$$y(t) = C_1 e^{(-2+3i)t} + C_2 e^{(-2-3i)t}$$

$$= C_1 e^{-2t} (\cos 3t + i \sin 3t) + C_2 e^{-2t} (\cos(-3t) + i \sin(-3t))$$

$$= C_1 e^{-2t} (\cos 3t + i \sin 3t) + C_2 e^{-2t} (\cos 3t - i \sin 3t)$$

$$= (C_1 + C_2) e^{-2t} \cos 3t + (iC_1 - iC_2) e^{-2t} \sin 3t$$

$$y(t) = A e^{-2t} \cos 3t + B e^{-2t} \sin 3t$$

$$\begin{cases} A = C_1 + C_2 \\ B = iC_1 - iC_2 \end{cases} \Leftrightarrow \begin{cases} C_1 = \frac{A - iB}{2} \\ C_2 = \frac{A + iB}{2} \end{cases}$$

$$e^{-2t} \cos 3t = \frac{1}{2} (e^{(-2+3i)t} + e^{(-2-3i)t})$$

$$e^{-2t} \sin 3t = \frac{1}{2i} (e^{(-2+3i)t} - e^{(-2-3i)t})$$

End of
Lecture 2

Ex 3: $y'' - 6y' + 9y = 0$

Char eqn: $r^2 - 6r + 9 = 0$

$$(r-3)^2 = 0$$

$$r = 3, 3$$

e^{3t} is a soln, but we need another

Solve diff. eqn iteratively

Differential operator D is defined as

$$Dy = y'$$

$$D^2y = D(Dy) = Dy' = y''$$

Ex 3 cont'd

$$0 = y'' - 6y' + 9y$$

$$= D^2y - 6Dy + 9y$$

$$= (D^2 - 6D + 9)y$$

check! \rightarrow $\textcircled{=}$ $(D-3)(D-3)y = (D-3)(y'-3y)$

$$= D(y'-3y) - 3(y'-3y)$$
$$= y'' - 3y' - 3y' + 9y$$
$$= y'' - 6y' + 9y$$

$$(D-3)(D-3)y = 0$$

$= u$

$$\left[\begin{array}{l} (D-3)u = 0 \\ u' - 3u = 0 \\ u' = 3u \\ u = Be^{3t} \end{array} \right.$$

$$u = (D-3)y$$

$$Be^{3t} = y' - 3y$$

$$y' - 3y = Be^{3t}$$

(1st order linear eqn)
see Ex 1 in §2.1 lecture

$$\boxed{y = Ae^{3t} + Bte^{3t}}$$

Nonhomog. eqn (§3.5)

Ex.: $y'' - 6y' + 9y = e^t$

$$(D^2 - 6D + 9)y = e^t$$

$$(D-3)(D-3)y = e^t$$

$= u$

$$\left[\begin{array}{l} (D-3)u = e^t \\ u' - 3u = e^t \quad (\text{1st order linear eqn}) \\ \text{Exercise: solve for } u \\ u = -\frac{1}{2}e^t + Be^{3t} \end{array} \right.$$

$$-\frac{1}{2}e^t + Be^{3t} = u = (D-3)y$$

$$y' - 3y = -\frac{1}{2}e^t + Be^{3t} \quad (\text{1st order linear eqn})$$

Exercise: solve for y

$$y(t) = Ae^{3t} + Bte^{3t} + \frac{1}{4}e^t$$