9.2.1 First order linear equations cont's  
\nMethod of integrating factors  
\nFor 1st order linear equations:  
\n
$$
pt\theta
$$
 at + Q(t) y = G(t) ,  $y(t_0) = y_0$   
\n
$$
\frac{dy}{dt} + \frac{Q(t)}{P(t)} y = \frac{G(t)}{P(t)}
$$
\n
$$
y' + q(t) y = g(t)
$$
\n
$$
I(t) (y' + q(t) y) = I(t)g(t)
$$
\n
$$
\int \frac{F \cdot d}{dt} I(t) s_t.
$$
\n
$$
\int \frac{F \cdot d}{t} I(t) = \int \frac{f(t)}{t} I(t) g(t) dt
$$
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\int \frac{d}{t} I(t) = g(t) I
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\n
$$
\int \frac{dI}{dt} = g(t) I
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\int \frac{dI}{dt} = \int g(t) dt
$$
\n
$$
\ln|I| = \int g(t) dt
$$
\n
$$
\int \frac{d}{t} I(t) = \int \frac{g(t) dt}{t} dt
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\int \frac{d}{t} I(t) = \int \frac{d
$$

$$
\frac{d(\overline{I}(t) y)}{dt} = It+g(t) \frac{Comment added after the lecture, \n
$$
\frac{d(\overline{I}(t) y)}{dt} = \int I(t)g(t) dt \text{ (also mentioned briefly last time)}:
$$
\n
$$
\int d(\overline{I}(t) y) = \int I(t)g(t)dt \text{ in the last lecture. \nThen  $\frac{du}{dt} = I(t)g(t)$ .
$$
\n
$$
\overline{I}(t) = \int I(t)g(t)dt \text{ so } u \text{ satisfies a simple eqn}
$$
\n
$$
\frac{du}{dt} = f(t).
$$
\n
$$
\frac{d(t) = \frac{1}{I(t)} \int I(t)g(t)dt}{\int I(t)g(t)dt} \text{ the soln is } u = \int f(t) dt.
$$
\n
$$
\frac{d(u}{dt} = f(t).
$$
\n
$$
\frac{d(t)}{dt} = \frac{1}{I(t)} \left( \int_{t_0}^t I(s)g(s)ds + C \right) \text{ [We find the method. \n
$$
\frac{d}{t} = \frac{1}{I(t)} \int_{t_0}^t I(s)g(s)ds + C \text{ [We find the method. \n
$$
\frac{d}{t} = \frac{1}{I(t)} \int_{t_0}^t I(s)g(s)ds + C \text{ [We find the method.}
$$
$$
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$$

$$
y_o = y(t_o) = \frac{1}{\mathcal{I}(t_o)} \left( o + C \right) = C
$$

$$
y(t) = \frac{1}{I(t)} \left( \int_{t_0}^t I(s) g(s) ds + y_o \right) \begin{pmatrix} 5 \sin t_0 \\ I \vee P \end{pmatrix}
$$

Conclusion: Existence & Uniqueness theorem for 1st order linear eqn

\nSuppose 
$$
q(t), q(t)
$$
 are continuous on an interval  $(a, b)$  and  $\Rightarrow$  then for any choice of initial value  $y(t_0) = y_0$ , there exists a unique solution  $y(t)$  on  $(a, b)$  satisfying  $y' + q(t)$   $y = g(t)$ ,  $y(t_0) = y_0$ .

$$
\underline{Ex}: t\overline{y}' + 2y = 4t^2, y(t) = 0, t > 0
$$
  

$$
y' + \frac{2}{t}y = 4t
$$
  

$$
I(t) = e^{\int 4t \cdot dt} = e^{\int \frac{2}{t} dt} = e^{2\ln|t|} = |t|^2 = t^2
$$

$$
t^{2}y' + 2ty = 4t^{3}
$$

$$
\frac{d(t^{2}y)}{dt} = 4t^{3}
$$

$$
\int d(t^{2}y) = \int 4t^{3} dt
$$

$$
t^{2}y = t^{4} + C
$$
  

$$
y(t) = t^{2} + \frac{c}{t^{2}}
$$

Or directly using formula:  
\n
$$
y(t) = \frac{1}{I(t)} \int I(t) g(t) dt
$$
\n
$$
= \frac{1}{t^{2}} \int t^{2} 4t dt = \frac{1}{t^{2}} \int 4t^{3} dt
$$
\n
$$
= \frac{1}{t^{2}} (t^{4} + c)
$$
\n
$$
= t^{2} + \frac{c}{t^{2}}
$$

$$
a = y(1) = 1 + \frac{C}{1} \implies C = a-1
$$
  

$$
y(t) = t^2 + \frac{a-1}{t^2}
$$

 $As t \rightarrow \infty$ , y(t)  $\rightarrow \infty$ 

As t→ 0, 
$$
y(t) \rightarrow \infty
$$
,  $a-1>0$ , i.e.  $a>1$   
 $y(t) \rightarrow -\infty$ ,  $a-1<0$ , i.e.  $a<1$   
 $y(t) \rightarrow 0$ ,  $a-1=0$ , i.e.  $a=1$ 

Remark: 
$$
ty' + 2y = 4t^2
$$

\nwhen  $t=0$ ,  $0 + 2y(0) = 0$ 

\n
$$
\Rightarrow y(0) = 0
$$
\nDirect in field:  $y' = 4t - \frac{2y}{t}$ 

\n $x y' = 0$ , when  $4t - \frac{2y}{t} = 0$ ,  $i.e.$   $\frac{y = 2t^2}{t}$ 

\nand a solo curve

$$
\frac{4}{3}y' > 0
$$
, when  $4t - 2\frac{y}{t} > 0$   
\n $\Rightarrow \frac{y}{t} < 2t \Rightarrow \begin{cases} y < 2t^2 \text{ when } t > 0 \\ y > 2t^2 \text{ when } t < 0 \end{cases}$ 

$$
\frac{4}{1}y^{1}<0
$$
, otherwise  
\n $y^{1}<\frac{1}{1}$   
\n $y^{1}<\frac{1}{1}$ 



Ex: IVP with nonlinear equi may not have a unique soln

$$
\frac{dy}{dt} = y^{1/3} , y(0) = 0 , t \ge 0
$$
  
separable : 
$$
\int y^{-1/3} dy = \int dt
$$

$$
\frac{3}{2}y^{2/3} = t + C
$$
  

$$
y^{2} = \left[\frac{2}{3}(t + c)\right]^{3/2}
$$
  

$$
y = \pm \left[\frac{2}{3}(t + c)\right]^{3/2}
$$
  

$$
y(0) = 0 \implies 0 = y(0) = \pm \left[\frac{2}{3}c\right]^{3/2}
$$
  

$$
\implies C = 0
$$
  

$$
y = \pm \left(\frac{2}{3}c\right)^{3/2}
$$



in fact, there are even more solv's See  $Ex3$  in  $$2.4$ 

Comment after the lecture: forgot to mention that it can be immediately seen the constant function Y(t) = 0 is also a solution. (there are many move Soln in  $Ex3524)$